

# Color-Shift-Keying Constellation-Design Case Studies

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**Abstract**—Color shift keying (CSK) is an emergent modulation for visible light wireless communication, whereby the light color is visibly constant. This paper presents several case studies of color-shift-keying constellations designed using various methods of constrained optimization to maximize the minimum Euclidean distance among the constellation symbols.

## I. MATHEMATICAL STATEMENT OF THE COLOR-SHIFT-KEYING CONSTELLATION DESIGN AS AN OPTIMIZATION PROBLEM

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The current problem is to design an  $M$ -ary constellation, with constellation points  $\{\mathbf{s}_m, \forall m = 1, 2, \dots, M\}$ , such that the constellation would give the largest “minimum distance” after passing through a channel with a known channel matrix of  $\mathbf{H}$ , while having each constellation symbol subject to a set of transmission power constraints and subject to one common color-constraint. The natural number  $M$  is generally a known positive power of 2 and is at least 4 (i.e.,  $M$  could be preset to a known value of 4 or 8 or 16, etc.).

Each constellation symbol  $\mathbf{s}_m$  is a  $3 \times 1$  vector,

$$\mathbf{s}_m := \begin{bmatrix} [\mathbf{s}_m]_r \\ [\mathbf{s}_m]_g \\ [\mathbf{s}_m]_b \end{bmatrix}, \quad (1)$$

with elements of non-negative scalars whose values are to be designed by maximizing the constellation’s “minimum distance”.

This maximization may be mathematically stated as

$$\arg \max_{\{\mathbf{s}_m, \forall m\}} \underbrace{\min_{\forall \mathbf{s}_j \neq \mathbf{s}_k} \overbrace{\|\mathbf{H}(\mathbf{s}_j - \mathbf{s}_k)\|_2}_{d_{j,k} :=}}_{\text{minimum distance}}, \quad (2)$$

where

$$\mathbf{H} := \begin{bmatrix} h_{r,r} & h_{r,g} & h_{r,b} \\ h_{g,r} & h_{g,g} & h_{g,b} \\ h_{b,r} & h_{b,g} & h_{b,b} \end{bmatrix} \quad (3)$$

represents a  $3 \times 3$  matrix of real-value scalars that are prior known.

The above maximization is subject to all six following constraints of (4) to (8):

Each constellation symbol  $\mathbf{s}_m$  must satisfy the following “power constraints”:

$$[\mathbf{s}_m]_r \in [0, I_r], \quad (4)$$

$$[\mathbf{s}_m]_g \in [0, I_g], \quad (5)$$

$$[\mathbf{s}_m]_b \in [0, I_b], \quad (6)$$

$$\|\mathbf{s}_m\|_1 \in [L_{\min}, L_{\max}], \quad (7)$$

$\forall m = 1, 2, \dots, M$ . Here, In the above,  $I_r, I_g, I_b, L_{\min}, L_{\max}, \eta_r, \eta_g, \eta_b$ , are all prior known and preset positive scalars. Oftentimes,  $I_r = I_g = I_b = L_{\max}$  and  $L_{\min} \approx L_{\max}$ .

Each constellation symbol  $\mathbf{s}_m$  must also satisfy the following “color constraint”:

$$\sum_{m=1}^M \mathbf{s}_i = LM\mathbf{d}, \quad (8)$$

with  $L$  and the vector  $\mathbf{d}$  preset.

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<sup>1</sup>This section is based on [1]–[3]. Please refer to them for details.

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## II. THE OPTIMIZATION STRATEGY

To numerically solve the abovementioned constrained optimization, the MATLAB built-in subroutine of “fmincon” will be used. This “fmincon” may be set by the human user to realize an “interior point method” (also called a “barrier method”) or an “active set” method. Both methods require the optimization problem to be convex, which is the optimization problem in Section I is not.

The “soft maximum” approximation is used in [1]–[3] to render Section I’s optimization problem to become convex. The “soft maximum” approximation identifies the maximum as  $\log \sum_{\forall j \neq k} e^{d_{j,k}}$ , instead of  $\max \{d_{j,k}, \forall j \neq k\}$ .

The stopping criteria of “fmincon” are subsequently set to

- (i) “TolCon” – the allowed constraint violation – is set to  $10^{-12}$ .
- (ii) “TolX” – the allowed variation in the output value – is set to  $10^{-15}$ .
- (iii) “TolFun” – the allowed constraint violation – is set to  $10^{-15}$ .

Both “interior point method” (IPM) and the “active set” method (ASM) are started off with a random estimate generated by the MATLAB command “randn”. As both methods are sensitive to the preset initial estimate, each method is run 30 times. Each  $d_{\min}$  value presented subsequently is the best obtained in all 30 runs.

## III. WHITE CSK CONSTELLATION FOR A NO-CROSS-TALK CHANNEL

The constellations below are designed for  $\mathbf{H} = \mathbf{I}$  (i.e. a channel with no coupling across the three LED-channels) and constrained to white light, i.e.  $\mathbf{d} = \frac{1}{3}[1, 1, 1]^T$ , where  $T$  denotes transposition. Moreover,  $L = 1.064$ ,  $L_{\min} = 0.9$  and  $I_r = I_g = I_b = L_{\max} = 1.1$ .

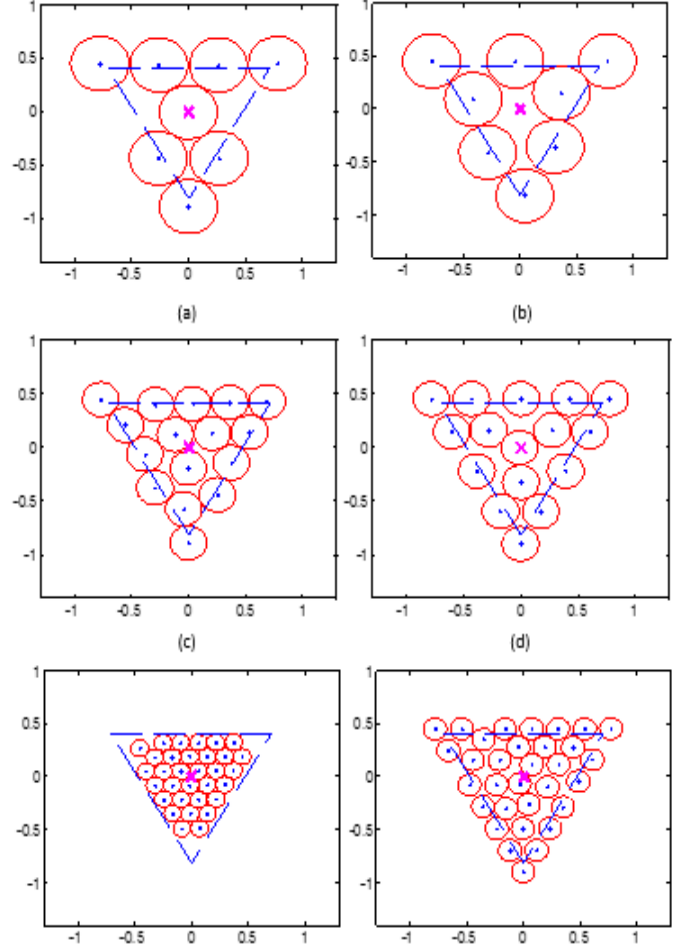


Fig. 1: Optimized constellation for  
(a)  $d_{\min} = 0.5236$  for  $M = 8$  by IPM,  
(b)  $d_{\min} = 0.5362$  for  $M = 8$  by ASM,  
(c)  $d_{\min} = 0.3190$  for  $M = 16$  by IPM,  
(d)  $d_{\min} = 0.3194$  for  $M = 16$  by ASM,  
(e)  $d_{\min} = 0.1532$  for  $M = 32$  by IPM,  
(f)  $d_{\min} = 0.2036$  for  $M = 32$  by ASM.

It may be observed that

- (i) The “active set” method consistently gives a larger  $d_{\min}$  than the “interior point method”
- (ii)  $d_{\min}$  decreases with an increasing  $M$ , as expected from the well known trade-off between bit-error rate and data rate.

#### IV. RED CSK CONSTELLATION FOR A CROSS-TALK CHANNEL

The constellations below are designed for  $\mathbf{H} \neq \mathbf{I}$  (i.e. a channel with coupling across the three LED-channels) and constrained to red light with  $\mathbf{d} = [0.3443, 0.4857, 0.1700]^T$ . The values for  $L, L_{\min}, L_{\max}, I_r, I_g$  and  $I_b$  are the same as in Section III.

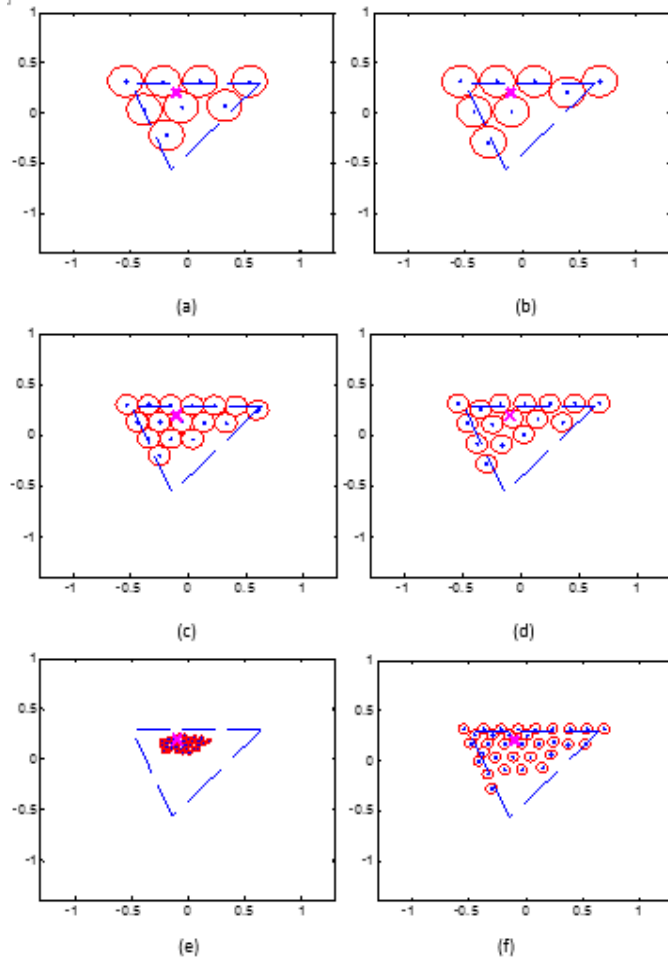


Fig. 2: Optimized constellation for

- (a)  $d_{\min} = 0.3072$  for  $M = 8$  by IPM,
- (b)  $d_{\min} = 0.3067$  for  $M = 8$  by ASM,
- (c)  $d_{\min} = 0.1895$  for  $M = 16$  by IPM,
- (d)  $d_{\min} = 0.1805$  for  $M = 16$  by ASM,
- (e)  $d_{\min} = 0.0422$  for  $M = 32$  by IPM,
- (f)  $d_{\min} = 0.0959$  for  $M = 32$  by ASM.

It may be observed that

- (i) For  $M = 32$  only, the “active set” method consistently gives a significantly larger  $d_{\min}$  than the “interior point method”. For  $M = 8$  and  $M = 16$ , the “active set” method consistently gives a slightly smaller  $d_{\min}$  than the “interior point method”.
- (ii) The  $d_{\min}$  is significant lower in this case of  $\mathbf{H} \neq \mathbf{I}$  and non-white light, than for Section III’s case of  $\mathbf{H} = \mathbf{I}$  and white light.
- (iii)  $d_{\min}$  decreases with an increasing  $M$ , as expected from the well known trade-off between bit-error rate and data

rate.

#### REFERENCES

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